Low-Level and Embedded Programming (2)

Real-Time and Embedded Systems (M) Lecture 19



Lecture Outline

- Hardware developments
- Implications on system design
 - Low-level programming
 - Automatic memory management
 - Timing
 - Concurrency
- Considerations for new system architectures



Low-Level and Embedded Programming

- Real time and embedded systems programming differs from conventional desktop applications programming
 - Must respect timing constraints
 - Must interact with environment
 - Often very sensitive to correctness and robust operation
 - Often very sensitive cost, weight, or power consumption
- Implications to consider:
 - Proofs of correctness, schedulability tests, etc.
 - Must consider system implementation issues, not just theory
 - Limited resources available
 - Low level programming environments typical
 - Require high awareness of system issues; interaction with hardware
 - Cannot necessarily depend on "common" language, operating system, or hardware features being present

Yes, but...

- Continued advances in hardware
 - Moore's "law" shows no sign of abating for some years yet
 - Increasing use of system-on-a-chip designs
 - Processor, memory, I/O devices integrated into a single chip package
 - Performance of low-cost embedded hardware increasing rapidly
- Where are corresponding advances in software?
 - Desirable to raise abstraction level
 - Ease program development and increase productivity
 - Modern software engineering techniques
 - High(er) level languages
 - E.g. Real Time Java
 - Simplify proofs of correctness
- How to improve real time & embedded systems implementation?

Copyright © 2007 University of Glasg All rights reserved.

Evolution of Real Time Systems

- Use increased system performance to enable:
 - Language support for low-level programming
 - Interrupt handling
 - Device access
 - Language support for automatic memory management
 - Real time garbage collection
 - Language support for timing
 - Timed periodic threads
 - Timed statements/timing annotations
 - Language support for concurrency
 - Problems with threads
 - Problems with synchronisation
- Use increased hardware performance to offset reduced software efficiency, gain programmer productivity

Copyright © 2007 University of Glasge All rights reserved.

Interrupt Handling

- Interrupt handling highly machine/operating system dependent
- Few systems support linking user code into interrupt handlers
 - Ada Real Time Systems annex a notable exception:

```
package Ada.Interrupts is
   type Interrupt_Id is ...;
   type Parameterless_Handler is access protected procedure;

function Is_Reserved(Interrupt:Interrupt_Id) return Boolean;
   function Is_Attached(Interrupt:Interrupt_Id) return Boolean;

function Current_Handler(Interrupt:Interrupt_Id) return Parameterless_Handler;

procedure Attach_Handler(Handler:Parameterless_Handler, Interrupt:Interrupt_Id);
   procedure Detach_Handler(Interrupt:Interrupt_Id);
   ...
end Ada.Interrupts;
```

- Possible to provide similar standard facilities in other languages
 - Some overhead since must vector through hardware abstraction layer; reasonable and safe to implement on microkernel
 - Could eliminate platform-specific hooks, allow portable code

Copyright © 2007 University of Glasga All rights reserved.

Device Drivers

- Seen various approaches to low-level device access
 - C-style: simple and expressive, non-portable
 - Ada: verbose, precise specification, portable
- Can language support help?
 - Clear that object-oriented ideas useful for device families:
 - MacOS X I/O Kit object oriented device drivers using a subset of C++
 - Linux uses object-based approach for many drivers, implemented in C
 - Higher performance, but MacOS X drivers easier to write
 - Ability to cleanly define inheritance and sub-class relationships, timeouts,
 state machines, and interrupt handlers at language level likely beneficial
 - Given wide range of embedded hardware, might be appropriate to sacrifice some performance for ease of development

Memory Management

- Strong distrust of managed languages, garbage collection, in real time systems community
 - E.g. Real Time Java memory model augmented with non-collected zones, manual memory management
- But: memory management problems abound
 - Memory leaks
 - Unpredictable memory allocation performance
 - Calls to malloc() can vary in execution time by several orders of magnitude
 - Memory corruption and buffer overflows

Can garbage collection and memory protection help?

Garbage Collection

- Traditional algorithms not suitable
 - Triggered at unpredictable times
 - Unpredictable collection delays since move objects to avoid fragmentation
- Real time garbage collection still an active research area
 - Two basic approaches:
 - Work based: every request to allocate an object or assign an object reference does some garbage collection; amortise collection cost with allocation cost
 - Time based: schedule an incremental collector as a periodic task
 - Easier to prove correctness
 - More predictable behaviour

D. Frampton, D. F. Bacon, P. Cheng, and D. Grove, "Generational Real-Time Garbage Collection: A Three-Part Invention for Young Objects", Proceedings 21st European Conference on Object Oriented Programming, Berlin, Germany, July 2007.

- Obtain timing guarantees only by limiting amount of garbage that can be collected in a given interval
 - Implication: user must indicate maximum memory consumption and allocation rate, to determine cost of the garbage collector
 - Workable solutions exist for many periodic applications; same issue as certain scheduling algorithms placing constraints on application design

Memory Protection

- Traditional memory protection unpredictable ⇒ problematic
 - Slows context switch and system call times
 - Requires illegal access traps and handler
 - Unpredictable
 - Difficult to implement error recovery
- Can guarantee safety without hardware protection:
 - Strongly typed language, checked array bounds, no pointer arithmetic
 - Closer to Java than to C
 - E.g. Singularity from Microsoft Research
 - Majority of system written in extended C# and .Net, small microkernel in C++
 - http://research.microsoft.com/os/singularity/
 - Much verification done at compile time; reduces run-time unpredictability
 - Higher overhead than current systems, but not excessive

Timing Annotations

- How to ensure predictable timing?
 - Extensive scheduler theory, proofs of schedulability
 - Introduce abstractions for timed threads into the language
 - E.g. Real Time Java
 - Add timing annotations to language, let compiler determine schedulability
 - Compiler *much* better at counting cycles than a human, due to complex processor architectures
 - Likely feasible to estimate worst-case execution time for many embedded codes; compare with task timing annotations
 - Computationally hard in general due to loops, etc.
 - Equivalent to halting problem for arbitrary code
 - Real systems often much more constrained: hard real time systems required to be provably correct
 - Helps debugging if not proving correctness

Timing Annotations

- To what extent possible to annotate timing requirements?
 - Properties of periodic tasks straight forward
 - Aperiodic/sporadic tasks harder, but often meaningful statistics
 - But what about low-level behaviour?
 - Annotate that an expression should take no more than *x* milliseconds
 - System call/library function timing
- What are hidden timing behaviours of system?
 - Scheduler and system call overhead
 - malloc()/free(), garbage collection
 - Cache, memory hierarchy, memory protection
 - Speculative execution, pipelining, super-scalar and out-of-order execution
- Programmers cannot count cycles; yet many still program as if it were possible – need compiler help

Support for Concurrency

- Concurrency increasingly important
 - Trends in microprocessor design
 - Asynchronous interactions with outside world
 - Threads and synchronisation primitives problematic
 - Low level model
 - Easy to make mistakes
 - Hard to reason about performance/correctness
 - Are there alternative architectures which avoid these issues?
 - Implicit concurrency; execution models which hide complexity
 - Functional and/or message passing algorithms
 - e.g. Ericsson AXD301 160 Gbps ATM switch has claimed 99.9999999% uptime and is (mostly) written in the Erlang functional programming language

Copyright © 2007 University of Glasg All rights reserved.

Reliability Through Clarity

- State and requirements hidden in existing code
 - Need to infer high-level goals from low-level implementation
- Yet Moore's law continues
 - Performance increasing for fixed price point, power consumption
- Better languages/libraries would allow programmers to express high-level goals, system to check implementation meets them
 - Requires paradigm shift away from current implementation strategies
 - Beginning to happen with Real Time Java; realisation that platforms both powerful and cost effective

Questions or Discussion?

Summary

- Development in hardware
- Implications on system design
 - Low-level programming
 - Automatic memory management
 - Timing
 - Concurrency
- Considerations for new system architectures

Further reading: Gay *et al*, "The nesC Language: A Holistic Approach to Networked Embedded Systems", Proc. PLDI'03.